



Operating Manual

Ultrasonic proximity switch with one switching output and IO-Link

- pico+15/F/A
- pico+25/F/A
- pico+35/F/A
- pico+100/F/A
- pico+15/WK/F/A
- pico+25/WK/F/A
- pico+35/WK/F/A
- pico+100/WK/F/A

Product description

The pico+ sensor offers a non-contact measurement of the distance to an object which must be positioned within the sensor's detection zone. The switching output is set conditional upon the adjusted detect distance. Via the Teach-in procedure, the detect distance and operating mode can be adjusted. Two LEDs indicate the state of the switching output.

IO-Link

The pico+ sensors are IO-Link-capable in accordance with IO-Link specification V1.1 and support Smart Sensor Profile like Digital Measuring Sensor.

Safety instructions

- Read the operating manual prior to start-up.
- Connection, installation and adjustments may only be carried out by qualified staff.
- No safety component in accordance with the EU Machine Directive, use in the area of personal and machine protection not permitted.

Use for intended purpose only

pico+ ultrasonic sensors are used for non-contact detection of objects.

Installation

- Mount the sensor at the place of fitting.
- Connect a connection cable to the M12 device plug, see Fig. 1.

microsonic notation	IO-Link notation	IO-Link Smart Sensor Profile	colour
1	+U _B	L+	brown
2	-	NC	white
3	-U _B	L-	blue
4	F	C/Q	black
5	Com	NC	grey

Fig. 1: Pin assignment with view onto sensor plug, IO-Link notation and colour coding of the microsonic connection cables.

Start-up

- Connect the power supply.
- Carry out sensor adjustment in accordance with Diagram 1.

Factory setting

- Switching point operation
- Switching output on NOC
- Detect distance at operating range
- Multi-function input »Com« set to »Teach-in« and »synchronisation«
- Filter at F01
- Filter strength at P00

Operating modes

Three operating modes are available for the switching output:

- Operation with one switching point**
The switching output is set when the object falls below the set switching point.
- Window mode**
The switching output is set when the object is outside the set window.

- Two-way reflective barrier**
The switching output is set when the object is between sensor and fixed reflector.

Synchronisation

If the assembly distance of multiple sensors falls below the values shown in Fig. 2, the internal synchronisation should be used. For this purpose set the switching outputs of all sensors in accordance with Diagram 1. Then switch-on the multi-function output »Com« to »Teach-in« and »synchronisation« (see »Further settings«, Diagram 1). Finally interconnect each pin 5 of the sensors to be synchronised.

pico+15...	≥0.25 m	≥1.30 m
pico+25...	≥0.35 m	≥2.50 m
pico+35...	≥0.40 m	≥2.50 m
pico+100...	≥0.70 m	≥4.00 m

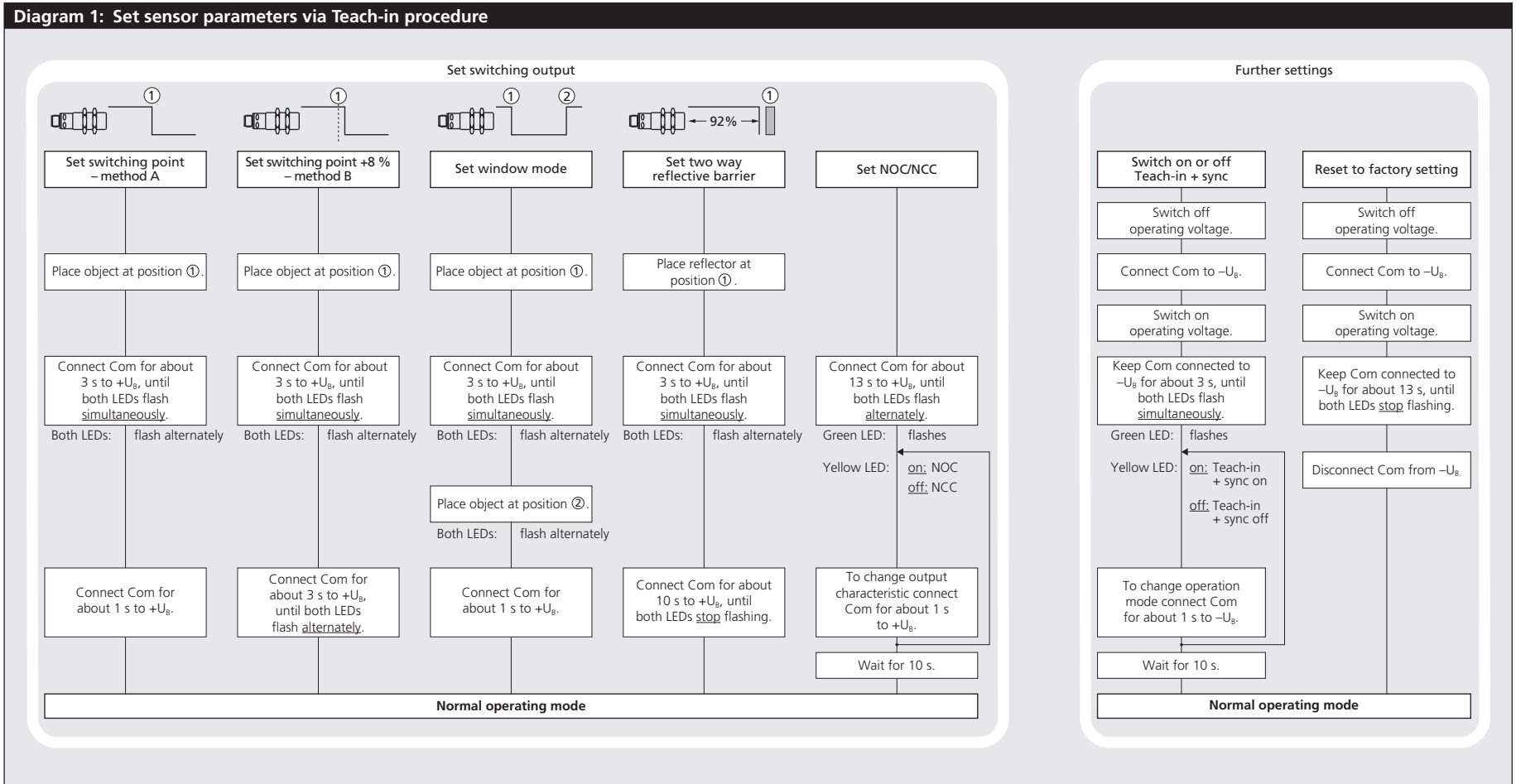
Fig. 2: Assembly distances.

Maintenance

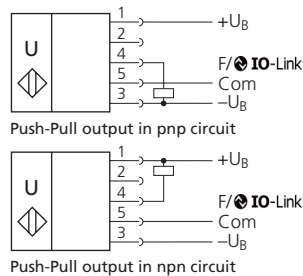
microsonic sensors are maintenance-free. In case of excess caked-on dirt we recommend cleaning the white sensor surface.

Notes

- The sensors of the pico+ family have a blind zone, within which a distance measurement is not possible.
- The pico+ sensors are equipped with an internal temperature compensation. Due to the sensors self heating, the temperature compensation reaches its optimum working-point after approx. 120 seconds of operation.
- In the normal operating mode, an illuminated yellow LED signals that the switching output is switched through.
- In the »Two-way reflective barrier« operating mode, the object has to be within the range of 0 to 92 % of the set distance.



Technical data

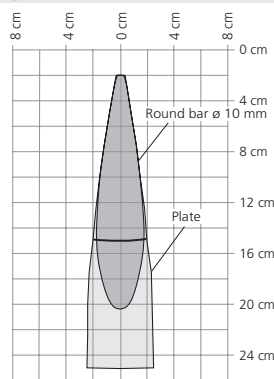


blind zone
operating range
maximum range
angle of beam spread
transducer frequency
resolution
reproducibility

20 mm
150 mm
250 mm
see detection zone
380 kHz
0.1 mm
±0.15 %

for different objects:

The dark grey areas represent the zone where it is easy to recognise the normal reflector (round bar). This indicates the typical operating range of the sensors. The light grey areas represent the zone where a very large reflector – for instance a plate – can still be recognised. The requirement here is for an optimum alignment to the sensor. It is not possible to evaluate ultrasonic reflections outside this area.



accuracy
operating voltage U_B
voltage ripple
no-load current consumption
housing

±1 % (temperature drift internally compensated)
10 bis 30 V DC, reverse polarity protection (Class 2)
±10 %
<40 mA
brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content
15 Nm
IP 67
5-pin M12 circular plug
Teach-in via pin 5 (Com)
LED green, LED yellow
Teach-in, LinkControl, IO-Link
internal synchronisation up to 10 sensors
operating temperature
-25 to +70 °C
storage temperature
-40 to +85 °C
Push-Pull, U_B -3 V, $-U_B$ +3 V, I_{max} = 100 mA
switchable NOC/NCC, short-circuit-proof

switching hysteresis¹⁾
switching frequency²⁾
response time²⁾
time delay before availability
norm conformity

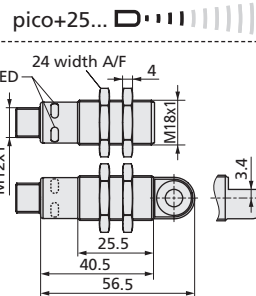
2 mm
25 Hz
32 ms
<300 ms
EN 60947-5-2

order no. directly radiating
weight

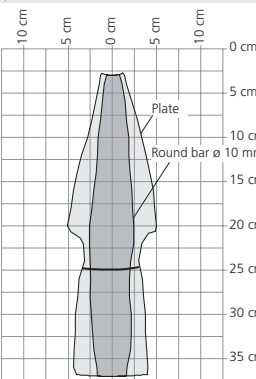
pico+15/F/A
30 g

order no. angular head
weight

pico+15/WK/F/A
35 g



30 mm
250 mm
350 mm
see detection zone
320 kHz
0.1 mm
±0.15 %



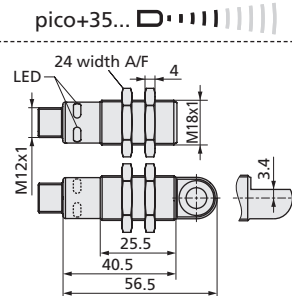
±1 % (temperature drift internally compensated)
10 bis 30 V DC, reverse polarity protection (Class 2)
±10 %
<40 mA
brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content
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5-pin M12 circular plug
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switchable NOC/NCC, short-circuit-proof

switching hysteresis¹⁾
switching frequency²⁾
response time²⁾
time delay before availability
norm conformity

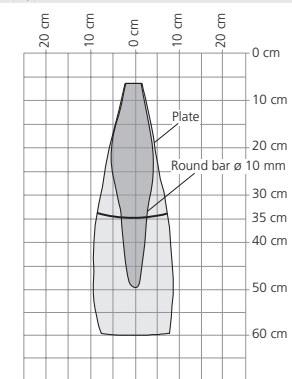
3 mm
25 Hz
32 ms
<300 ms
EN 60947-5-2

pico+25/F/A
30 g

pico+25/WK/F/A
35 g



65 mm
350 mm
600 mm
see detection zone
400 kHz
0.1 mm
±0.15 %



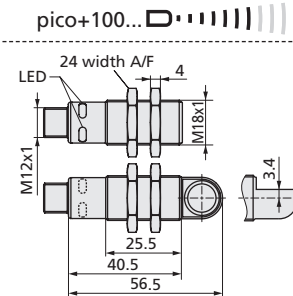
±1 % (temperature drift internally compensated)
10 bis 30 V DC, reverse polarity protection (Class 2)
±10 %
<40 mA
brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content
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switchable NOC/NCC, short-circuit-proof

switching hysteresis¹⁾
switching frequency²⁾
response time²⁾
time delay before availability
norm conformity

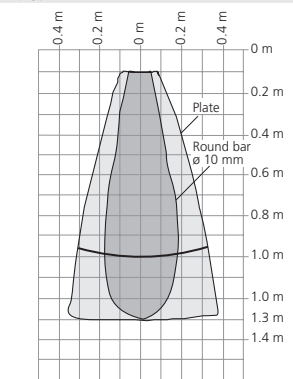
5 mm
12 Hz
64 ms
<300 ms
EN 60947-5-2

pico+35/F/A
30 g

pico+35/WK/F/A
35 g



120 mm
1,000 mm
1,300 mm
see detection zone
200 kHz
0.1 mm
±0.15 %



±1 % (temperature drift internally compensated)
10 bis 30 V DC, reverse polarity protection (Class 2)
±10 %
<40 mA
brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content
15 Nm
IP 67
5-pin M12 circular plug
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switchable NOC/NCC, short-circuit-proof

switching hysteresis¹⁾
switching frequency²⁾
response time²⁾
time delay before availability
norm conformity

20 mm
10 Hz
80 ms
<300 ms
EN 60947-5-2

pico+100/F/A
30 g

pico+100/WK/F/A
35 g

■ In the »Set switching point – method A« Teach-in procedure the actual distance to the object is taught to the sensor as the detect point. If the object moves towards the sensor (e.g. with level control) then the taught distance is the level at which the sensor has to switch the output.

■ If the object to be scanned moves into the detection area from the side, the »Set switching point +8 % – method B« Teach-in procedure should be used. In this way the switching distance is set 8 % further than the actual measured distance to the object. This ensures a reliable switching distance even if the height of the objects varies slightly.

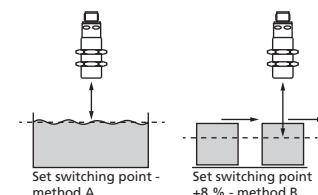


Fig. 3: Setting the switching point for different directions of movement of the object

■ The sensor can be reset to its factory setting (see »Further settings«).

■ Using the LinkControl adapter (optional accessory) and the LinkControl software for Windows®, all Teach-in and additional sensor parameter settings can be optionally adjusted.

■ The pico+ sensors have a push-pull switching output.

■ The latest IODD file and informations about start-up and configuration of pico+ sensors with IO-Link, you will find online at www.microsonic.de/en/pico+.